

# Package: tfNeuralODE (via r-universe)

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**Type** Package

**Title** Create Neural Ordinary Differential Equations with 'tensorflow'

**Version** 0.1.0

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**Description** Provides a framework for the creation and use of Neural ordinary differential equations with the 'tensorflow' and 'keras' packages. The idea of Neural ordinary differential equations comes from Chen et al. (2018) [doi:10.48550/arXiv.1806.07366](https://doi.org/10.48550/arXiv.1806.07366), and presents a novel way of learning and solving differential systems.

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**Encoding** UTF-8

**Imports** tensorflow, keras, reticulate, deSolve

**RoxygenNote** 7.2.3

**Suggests** knitr, rmarkdown, testthat (>= 3.0.0)

**Config/testthat.edition** 3

**VignetteBuilder** knitr

**URL** <https://github.com/semrang9/tfNeuralODE>

**BugReports** <https://github.com/semrang9/tfNeuralODE/issues>

**Repository** <https://semrang9.r-universe.dev>

**RemoteUrl** <https://github.com/semrang9/tfneuralode>

**RemoteRef** HEAD

**RemoteSha** e749a71f97ca6facd5af1d45ad4cf27d75a11d41

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backward

*Backward pass of the Neural ODE***Description**

Backward pass of the Neural ODE

**Usage**

```
backward(model, tsteps, outputs, output_gradients = NULL)
```

**Arguments**

<code>model</code>	A keras neural network that defines the Neural ODE.
<code>tsteps</code>	A vector of each time step upon which the Neural ODE is solved to get to the final solution.
<code>outputs</code>	The tensor outputs of the forward pass of the Neural ODE.
<code>output_gradients</code>	The tensor gradients of the loss function.

**Value**

The model input at the last time step.

The gradient of loss with respect to the inputs for use with the Adjoint Method.

The gradients of loss the neural ODE.

**Examples**

```
reticulate::py_module_available("tensorflow")

# example code
# single training example
OdeModel(keras$Model) %py_class% {
  initialize <- function() {
    super$initialize()
    self$block_1 <- layer_dense(units = 50, activation = 'tanh')
    self$block_2 <- layer_dense(units = 2, activation = 'linear')
  }

  call <- function(inputs) {
    x<- inputs ^ 3
    x <- self$block_1(x)
    self$block_2(x)
  }
}
tsteps <- seq(0, 2.5, by = 2.5/10)
true_y0 = t(c(2., 0.))
```

```

model<- OdeModel()
optimizer = tf$keras$optimizers$legacy$Adam(learning_rate = 1e-3)
# single training iteration
pred = forward(model, true_y0, tsteps)
with(tf$GradientTape() %as% tape, {
  tape$watch(pred)
  loss = tf$reduce_mean(tf$abs(pred - inp[[2]]))
})
dLoss = tape$gradient(loss, pred)
list_w = backward(model, tsteps[1:batch_time], pred, output_gradients = dLoss)
optimizer$apply_gradients(zip_lists(list_w[[3]], model$trainable_variables))

```

**forward***Forward pass of the Neural ODE network***Description**

Forward pass of the Neural ODE network

**Usage**

```
forward(model, inputs, tsteps, return_states = FALSE)
```

**Arguments**

<code>model</code>	A keras neural network that defines the Neural ODE.
<code>inputs</code>	Matrix or vector inputs to the neural network.
<code>tsteps</code>	A vector of each time step upon which the Neural ODE is solved to get to the final solution.
<code>return_states</code>	A boolean which dictates whether the intermediary states between the input and the final solution are returned.

**Value**

solution of the forward pass of Neural ODE

**Examples**

```

reticulate::py_module_available("tensorflow")

# example code

library(tensorflow)
library(keras)

OdeModel(keras$Model) %py_class% {
  initialize <- function() {

```

```

super$initialize()
self$block_1 <- layer_dense(units = 50, activation = 'tanh')
self$block_2 <- layer_dense(units = 2, activation = 'linear')
}

call <- function(inputs) {
  x<- inputs ^ 3
  x <- self$block_1(x)
  self$block_2(x)
}
}
tsteps <- seq(0, 2.5, by = 2.5/10)
true_y0 = t(c(2., 0.))
model<- OdeModel()
forward(model, true_y0, tsteps)

```

**rk4\_step***Runge Kutta solver for ordinary differential equations***Description**

Runge Kutta solver for ordinary differential equations

**Usage**

```
rk4_step(func, dt, state)
```

**Arguments**

<code>func</code>	The function to be numerically integrated.
<code>dt</code>	Time step.
<code>state</code>	A list describing the state of the function, with the first element being 1, and the second being a tensor that represents state

**Value**

A list containing a new time and the numerical integration of the function across the time step to the new time.

**Examples**

```

reticulate::py_module_available("tensorflow")
# example code
library(tensorflow)
ode_fun<- function(u){
  r = u ^ 3
  true_A = rbind(c(-0.1, 2.0), c(-2.0, -0.1))

```

```
du <- r %*% (true_A)
return(as.matrix(du))
}
y<- tensorflow::tf$cast(t(as.matrix(c(2, 0))), dtype = tf$float32)
x<- rk4_step(ode_fun, dt = 0.25,
              state = list(1.0, y))
x
```

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